Replica Method for Sparse Representation of White Gaussian Noise with Application to Noisy Compressed Sensing

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 - Sharp threshold for ℓ₀-norm decoding in noisy compressed sensing (viz. underdetermined Gaussian vector channels)
 - and its mean-square error performance

Acknowledgment for useful discussions

- ► Ido Kanter (BIU)
- ► Noam Shental (Open U.)
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Rick Chartrand (LANL)

Outline

Introduction

Sparse representation of WGN

Noisy compressed sensing

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Noisy compressed sensing

► Let $\mathbf{w} \in \mathbb{R}^m$ be a WGN vector with i.i.d. $w_i \sim \mathcal{N}(0, 1)$, i = 1, ..., m

► Choose an overcomplete dictionary D ∈ ℝ^{m×n}, m ≤ n, with zero-mean, unit-variance, i.i.d. D_{ij}, j = 1,..., n

▶ e.g. Gaussian $D_{ij} \sim \mathcal{N}(0,1)$, Bernoulli $D_{ij} = \pm 1$

▶ w and D are statistically independent

The realizations of the WGN, w, and dictionary, D, are denoted by ω and D, respectively.



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▶ Let $z(\omega, \mathcal{D}) \in \mathbb{R}^n$ be a representation of a WGN vector via a dictionary, namely

$$\omega = rac{1}{\sqrt{n}}\mathcal{D}\mathsf{z}$$

► z_k(ω, D) is termed k-sparse representation if at most k ≤ n of its entries are non-zero



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Large-system limit

Our analysis assumes:

- ▶ $m, n, k \to \infty$
- Measurement ratio $lpha riangleq m/n \in (0,1)$
- Sparsity fraction $\kappa \triangleq k/n \in (0,1)$



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Example: ($\kappa = 1$)-sparse (dense) representation



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► For example:

$$z_n \sim \mathcal{N}(\mathbf{0}, \mathbf{I}) \Rightarrow \mathbf{w} \sim \mathcal{N}(\mathbf{0}, \mathbf{D}\mathbf{D}^T/n) \xrightarrow[\alpha \in (0,1)]{m,n \to \infty} \mathcal{N}(\mathbf{0}, \mathbf{I})$$

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Another example: $(\kappa = \alpha)$ -sparse representation

Trivially, one can also represent (almost surely) the WGN vector using only m out of n entries



Motivation

But can we go below this trivial sparsity?



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Motivation

 Intriguingly the answer is yes: as we shall see, there are sparser representations of WGN with some interesting characteristics



Problem formulation

• What is the normalized Hamming weight (sparsity fraction) $\kappa^*_{\alpha}(\boldsymbol{\omega}, \boldsymbol{\mathcal{D}})$ of the sparsest representation of WGN based on an α -measurement dictionary in the limit of large systems?

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where $\|\mathbf{z}\|_{0} \triangleq \#\{i \in \{1, ..., n\} \mid z_{i} \neq 0\}$

Problem reformulation

What is the normalized Hamming weight (sparsity fraction) κ^{*}_α of the <u>sparsest</u> representation of WGN based on an α-measurement dictionary in the limit of large systems?

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Assumption (Self-averaging property)

The limit $\kappa_{\alpha}^{*} \triangleq \lim_{n\to\infty} \kappa_{\alpha}^{*}(\omega, \mathcal{D})$ exists and it is equal to its average over the randomness of the WGN and dictionary, $\lim_{n\to\infty} \mathbb{E}_{\mathbf{w},\mathbf{D}} \{\kappa_{\alpha}^{*}(\omega, \mathcal{D})\}$, for almost all realizations of the WGN and dictionary.

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Illustration



 Introducing the achievable and converse regions for sparse representation of WGN

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Illustration



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Proposition (Sparsest representation of WGN)

Consider the scalars $\alpha \in (0, 1)$ and $\kappa_{\alpha}^* \triangleq 2\mathcal{Q}(\xi) \in (0, 1)$, where $\xi \ge 0$ is determined by

$$lpha = \sqrt{rac{2}{\pi}} \int_{\xi}^{\infty} t^2 \exp{(-t^2/2)} dt,$$

and $Q(\xi) \triangleq \int_{\xi}^{\infty} dt / \sqrt{2\pi} \exp(-t^2/2)$ is the Q-function. Then, with probability 1 in the large-system limit, for a dictionary **D** with measurement ratio α :

- i) minimal Hamming weight: the sparsest WGN representation is $\kappa^*_\alpha\text{-sparse};$
- ii) achievable region: κ -sparse representation of WGN exists only for $\kappa \geq \kappa_{\alpha}^{*}$;
- iii) converse region: κ -sparse representation of WGN does not exist for $\kappa < \kappa_{\alpha}^{*}$.
Sparsest representation of WGN

- Proof is based on the Replica method from statistical mechanics (Replica-symmetric ansatz)
- Replica method is mathematically non-rigorous, but shown to be very powerful tool

Achieving distribution of WGN sparse representation

What is the probability density function of the WGN κ-sparse representation via α-measurement dictionary? Achieving distribution of WGN sparse representation

Proposition

The marginal probability density function of the j'th (non-zero) entry, ζ_j , of the (minimal ℓ_2 -norm) κ -sparse representation of WGN, z_{κ} , is given in the large-system limit by

$$p(\zeta_j) = \begin{cases} 0 & \text{if } |\zeta_j| < \xi \sqrt{\frac{\alpha}{\alpha_{\kappa}^*(\alpha_{\kappa}^* - \alpha)}} \\ \sqrt{\frac{\alpha_{\kappa}^*(\alpha_{\kappa}^* - \alpha)}{2\pi\alpha\kappa^2}} \exp\left(-\frac{\zeta_j^2 \alpha_{\kappa}^*(\alpha_{\kappa}^* - \alpha)}{2\alpha}\right) & \text{otherwise} \end{cases},$$

where α_{κ}^{*} is the achievability threshold for given sparsity fraction κ .

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Proof is also based on Replica analysis





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- A → a^{*} ⇒ The gap increases to infinity and the non-vanishing part (Gaussian tail) of the distribution becomes more uniform
- The marginal probability is symmetric
- In the large-system limit, the achieving distribution is <u>not</u> a function of the WGN and Gaussian dictionary realizations
- There is an infinite number of sparse representations per (κ, α)-point in the achievable region
- The stated achieving distribution corresponds to the minimal l₂-norm representation
- What is the pairwise/joint distribution of ζ? interesting (yet challenging) open question

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Generate WGN vector w=randn(m,1) and Gaussian dictionary D=randn(m,n)

► Estimate the sparsest representation per w and D realization using the iteratively reweighted least-squares (IRLS) method, which is an approximation of lo-norm minimization

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Average over realizations

Experimental study: results

- ▶ Quadratic curve fitting is used to extrapolate threshold for $n \to \infty$
- ► For example:



Experimental study: results



- Fairly good agreement
- ► Mismatch due to extrapolation errors and IRLS approximation

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- Generate sparse representation z according to the Proposition (non-zero entry locations are chosen uniformly)
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- Build histogram for w

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Experimental study: results



Mismatch is mainly due to the inaccurate assumption that the non-zero entries of the sparse representation, z_i, are i.i.d.

So what we have learned so far?

- The minimal Hamming weight of sparse representation of WGN
- ► The marginal distribution of such sparse representations

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Outline

Introduction

Sparse representation of WGN

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Noisy compressed sensing

Let x_k be a k-sparse n-length vector

- Underdetermined linear transformation $\mathcal{D}x_k$ is observed
- ▶ Reconstruction with ℓ₀-norm

 $\hat{\mathbf{x}} = \arg\min \|\mathbf{x}\|_0$ subject to $\mathcal{D}\mathbf{x}_k = \mathcal{D}\mathbf{x}$

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• Prefect reconstruction $\hat{\mathbf{x}} = \mathbf{x}_k$ is possible with probability 1 if

- $m \ge k + 1$ for almost any \mathbf{x}_k (weak achievable region)
- *m* ≥ 2*k* for any x_k (strong achievable region)
- ▶ Reconstruction is impossible with overwhelming probability for m ≤ k (strong converse region)



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 ℓ_0 -norm optimization complexity

$\hat{\mathbf{x}} = rgmin \|\mathbf{x}\|_0$ subject to $\mathcal{D}\mathbf{x}_k = \mathcal{D}\mathbf{x}$

Prohibitively complex optimization problem

- NP-complete: requires combinatorial enumeration of the possible sparse vectors
- Still of theoretical importance and may lead to practical consequences and insights (e.g., bounds performance of tractable reconstruction methods, like l₁ - norm optimization)

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The CS "wonder"

• Reconstruction with ℓ_1 -norm

 $\hat{\mathbf{x}} = \arg\min \|\mathbf{x}\|_1$ subject to $\mathcal{D}\mathbf{x}_k = \mathcal{D}\mathbf{x}$

where $\|\mathbf{x}\|_1 \triangleq \sum_i |x_i|$

- ▶ Prefect reconstruction x̂ = x_k is possible with probability 1 at the cost of more required measurements w.r.t. ℓ₀-norm minimization
- ► However the l₁-norm optimization problem is tractable with polynomial complexity

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Underdetermined (overloaded) Gaussian vector channel

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- ► Input x is κ_x-sparse
- $\mathbb{E}\{x_i^2\}$ is finite
- Examples of overloaded Gaussian channels:

D	m	n
CDMA spreading matrix	processing gain	users
MIMO fading channel	rx. antennas	tx. antennas

Noisy compressed sensing via WGN sparse representation

▶ Let $\mathbf{z}_{k^*_{\alpha}} \in \mathbb{R}^n$ be a k^*_{α} -sparsest WGN representation

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▶ Let $\mathsf{z}_{k^*_{\alpha}} \in \mathbb{R}^n$ be a k^*_{α} -sparsest WGN representation

Thus for the dictionary/channel D

$$\mathbf{y} = \sqrt{\frac{\operatorname{snr}}{m}} \mathbf{D} \mathbf{x} + \mathbf{w} = \sqrt{\frac{1}{m}} \mathbf{D} (\sqrt{\operatorname{snr}} \mathbf{x} + \sqrt{\alpha} \mathbf{z}_{k_{\alpha}^*}) = \sqrt{\frac{1}{m}} \mathbf{D} \mathbf{x}^*$$

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x* is the sparsest representation of the observations y w.r.t. the dictionary/channel D

From noisy to "noiseless" channel



► The noisy channel with κ_x-sparse input is translated into a noiseless channel with (κ_x + κ^{*}_α - κ_xκ^{*}_α)-sparse input



$$\begin{aligned} \kappa_{\alpha}^{*} + \kappa_{x} - \kappa_{\alpha}^{*}\kappa_{x} &\leq \alpha \\ \Rightarrow \kappa_{x} &\leq \frac{\alpha - \kappa_{\alpha}^{*}}{1 - \kappa_{\alpha}^{*}} \end{aligned}$$

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► Insensitive to snr: same decodable region for all SNR

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 The support Ω₀ of x* is now known, thus the problem is well-posed and one could reconstruct x with Least-Squares method

$$\hat{x}_{LS} = \left\{ \begin{array}{ll} \sqrt{\frac{m}{\mathsf{snr}}} (\mathsf{D}_{\Omega_0}^{\mathsf{T}} \mathsf{D}_{\Omega_0})^{-1} \mathsf{D}_{\Omega_0}^{\mathsf{T}} \mathsf{y} & \text{on } \Omega_0 \\ 0 & \text{elsewhere} \end{array} \right.$$

Proposition

Given a Gaussian vector channel with measurement ratio $\alpha \in (0, 1)$ and arbitrary snr > 0, then in the large-system limit an ℓ_0 -norm decoder results, with probability 1, in average mean-square error (MSE) per unknown

$$\frac{1}{n}\|\hat{\mathbf{x}}-\mathbf{x}\|_2^2 = \frac{\kappa_x + \kappa_\alpha^* - \kappa_x \kappa_\alpha^*}{snr},$$

as long as

$$\kappa_{\mathbf{x}} \leq \frac{\alpha - \kappa_{\alpha}^*}{1 - \kappa_{\alpha}^*}$$

for almost any x. Otherwise ℓ_0 -reconstruction is impossible with overwhelming probability.

► In the absence of any other (prior) information, reconstruction with MSE proportional to the noise level, as happens for ℓ₀-norm decoding, is the best one can hope for

$$\mathsf{MSE}_{\ell_0} = \frac{\kappa_x + \kappa^* - \kappa_x \kappa^*}{\mathsf{snr}} \ge \frac{\kappa_x}{\mathsf{snr}} = \mathsf{MSE}_{\mathsf{oracle}}$$

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Universality

► For any orthonormal basis matrix Ψ (e.g., DFT matrix) and a Gaussian dictionary D, the matrix DΨ will be also a Gaussian dictionary

 Introducing achievable and converse regions for sparse representation of WGN via Replica method

- The marginal distribution of such sparse representations is derived
- ► Introducing sharp threshold for ℓ₀-norm decoding in noisy compressed sensing
- ► The MSE of l₀-norm decoder in underdetermined Gaussian vector channels is

$$\frac{\kappa_{\rm x} + \kappa_{\alpha}^* - \kappa_{\rm x} \kappa_{\alpha}^*}{{\rm snr}}$$

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- ► Questions?
- ► E-mail: oshental@qualcomm.com

THANK YOU!